

**AFFILIATED INSTITUTIONS
ANNA UNIVERSITY, CHENNAI
REGULATIONS – 2013**

**M.E. POWER SYSTEMS ENGINEERING
I TO IV SEMESTERS (FULL TIME) CURRICULUM AND SYLLABUS
SEMESTER I**

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
THEORY						
1	MA7163	Applied Mathematics for Electrical Engineers	3	1	0	4
2	PS7101	Advanced Power System Analysis	3	1	0	4
3	PS7102	Power System Operation and Control	3	0	0	3
4	PS7103	Electrical Transients in Power Systems	3	0	0	3
5	CL7103	System Theory	3	0	0	3
6		Elective I	3	0	0	3
PRACTICAL						
7	PS7111	Power System Simulation Laboratory	0	0	3	1
TOTAL			18	2	3	21

SEMESTER II

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
THEORY						
1	PS7201	Power System Dynamics	3	0	0	3
2	PS7202	Flexible AC Transmission Systems	3	0	0	3
3	PS7203	Advanced Power System Protection	3	0	0	3
4	PS7204	Restructured Power System	3	0	0	3
5		Elective II	3	0	0	3
6		Elective III	3	0	0	3
PRACTICAL						
7	PS7211	Advanced Power System Simulation Laboratory	0	0	3	1
TOTAL			18	0	3	19

SEMESTER III

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
THEORY						
1		Elective IV	3	0	0	3
2		Elective V	3	0	0	3
3		Elective VI	3	0	0	3
PRACTICAL						
4	PS7311	Project work (Phase I)	0	0	12	6
TOTAL			9	0	12	15

SEMESTER IV

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
PRACTICAL						
1	PS7411	Project work (Phase II)	0	0	24	12
TOTAL			0	0	24	12

TOTAL NUMBER OF CREDITS = 67

ELECTIVES OF POWER SYSTEMS ENGINEERING

SL.NO.	COURSE CODE	COURSE TITLE	L	T	P	C
ELECTIVE I						
1.	ET7102	Microcontroller Based System Design	3	0	0	3
2.	PX7101	Analysis of Electrical Machines	3	0	0	3
3.	PX7103	Analysis and Design of Inverters	3	0	0	3

ELECTIVE II & III						
1.	PX7204	Power Quality	3	0	0	3
2.	PS7001	Optimization Techniques	3	0	0	3
3.	CL7204	Soft Computing Techniques	3	0	0	3
4.	PS7002	Energy Management and Auditing	3	0	0	3
5.	ET7006	Advanced Digital Signal Processing	3	0	0	3
6.	PS7003	Distributed Generation and Micro Grid	3	0	0	3

ELECTIVE IV,V & VI						
1.	PS7004	Solar and Energy Storage Systems	3	0	0	3
2.	PS7005	High Voltage Direct Current Transmission	3	0	0	3
3.	PS7006	Industrial Power System Analysis and Design	3	0	0	3
4.	PS7007	Wind Energy Conversion Systems	3	0	0	3
5.	PS7008	Smart Grid	3	0	0	3
6.	PS7009	Advanced Power System Dynamics	3	0	0	3
7.	PX7301	Power Electronics for Renewable Energy Systems	3	0	0	3
8.	ET7014	Application of MEMS Technology	3	0	0	3
9.	PS7010	Power System Planning and Reliability	3	0	0	3

6. Elsgolts, L., Differential Equations and the Calculus of Variations, MIR Publishers, Moscow, 1973.
7. Grewal, B.S., Higher Engineering Mathematics, 42nd edition, Khanna Publishers, 2012.
8. O'Neil, P.V., Advanced Engineering Mathematics, Thomson Asia Pvt. Ltd., Singapore, 2003.
9. Johnson R. A. and Gupta C. B., "Miller & Freund's Probability and Statistics for Engineers", Pearson Education, Asia, 7th Edition, 2007.

PS7101

ADVANCED POWER SYSTEM ANALYSIS

L T P C
3 1 0 4

OBJECTIVES

- To Introduce different techniques of dealing with sparse matrix for large scale power systems.
- To impart in-depth knowledge on different methods of power flow solutions.
- To perform optimal power flow solutions in detail.
- To perform short circuit fault analysis and understand the consequence of different type of faults.
- To Illustrate different numeric al integration methods and factors influencing transient stability

UNIT I SOLUTION TECHNIQUE

9

Sparse Matrix techniques for large scale power systems: Optimal ordering schemes for preserving sparsity. Flexible packed storage scheme for storing matrix as compact arrays – Factorization by Bifactorization and Gauss elimination methods; Repeat solution using Left and Right factors and L and U matrices.

UNIT II POWER FLOW ANALYSIS

9

Power flow equation in real and polar forms; Review of Newton's method for solution; Adjustment of P-V buses; Review of Fast Decoupled Power Flow method; Sensitivity factors for P-V bus adjustment.

UNIT III OPTIMAL POWER FLOW

9

Problem statement; Solution of Optimal Power Flow (OPF) – The gradient method, Newton's method, Linear Sensitivity Analysis; LP methods – With real power variables only – LP method with AC power flow variables and detailed cost functions; Security constrained Optimal Power Flow; Interior point algorithm; Bus Incremental costs.

UNIT IV SHORT CIRCUIT ANALYSIS

9

Formation of bus impedance matrix with mutual coupling (single phase basis and three phase basis) - Computer method for fault analysis using Z_{BUS} and sequence components. Derivation of equations for bus voltages, fault current and line currents, both in sequence and phase – symmetrical and unsymmetrical faults.

UNIT V TRANSIENT STABILITY ANALYSIS

9

Introduction, Numerical Integration Methods: Euler and Fourth Order Runge-Kutta methods, Algorithm for simulation of SMIB and multi-machine system with classical synchronous machine model ; Factors influencing transient stability, Numerical stability and implicit Integration methods.

L:45 +T: 15 TOTAL: 60 PERIODS

REFERENCES:

1. A.J.Wood and B.F.Wollenberg, "Power Generation Operation and Control", John Wiley and sons, New York, 1996.
2. W.F.Tinney and W.S.Meyer, "Solution of Large Sparse System by Ordered Triangular Factorization" IEEE Trans. on Automatic Control, Vol : AC-18, pp:333-346, Aug 1973.
3. K.Zollenkopf, "Bi-Factorization: Basic Computational Algorithm and Programming Techniques ; pp:75-96 ; Book on "Large Sparse Set of Linear Systems" Editor: J.K.Rerd, Academic Press, 1971.
4. M.A.Pai, "Computer Techniques in Power System Analysis", Tata McGraw-Hill Publishing Company Limited, New Delhi, 2006
5. G W Stagg , A.H El. Abiad "Computer Methods in Power System Analysis", McGraw Hill, 1968.
6. P.Kundur, "Power System Stability and Control", McGraw Hill, 1994.

PS7102

POWER SYSTEM OPERATION AND CONTROL

L T P C

3 0 0 3

COURSE OBJECTIVES

- To understand the fundamentals of speed governing system and the concept of control areas.
- To provide knowledge about Hydrothermal scheduling, Unit commitment and solution techniques.
- To understand the role of energy control center, SCADA and EMS functions.

UNIT I INTRODUCTION

9

System load variation: System load characteristics, load curves - daily, weekly and annual, load-duration curve, load factor, diversity factor. Reserve requirements: Installed reserves, spinning reserves, cold reserves, hot reserves. Overview of system operation: Load forecasting, techniques of forecasting, basics of power system operation and control.

UNIT II REAL POWER - FREQUENCY CONTROL

9

Fundamentals of speed governing mechanism and modelling: Speed-load characteristics – Load sharing between two synchronous machines in parallel; concept of control area, LFC control of a single-area system: Static and dynamic analysis of uncontrolled and controlled cases, Economic Dispatch Control. Multi-area systems: Two-

area system modelling; static analysis, uncontrolled case; tie line with frequency bias control of two-area system derivation, state variable model.

UNIT III HYDROTHERMAL SCHEDULING PROBLEM 9

Hydrothermal scheduling problem: short term and long term-mathematical model, algorithm. Dynamic programming solution methodology for Hydro-thermal scheduling with pumped hydro plant: Optimization with pumped hydro plant-Scheduling of systems with pumped hydro plant during off-peak seasons: algorithm. Selection of initial feasible trajectory for pumped hydro plant- Pumped hydro plant as spinning reserve unit-generation of outage induced constraint-Pumped hydro plant as Load management plant.

UNIT IV UNIT COMMITMENT AND ECONOMIC DISPATCH 9

Statement of Unit Commitment (UC) problem; constraints in UC: spinning reserve, thermal unit constraints, hydro constraints, fuel constraints and other constraints; UC solution methods: Priority-list methods, forward dynamic programming approach, numerical problems .Incremental cost curve, co-ordination equations without loss and with loss, solution by direct method and λ -iteration method. Base point and participation factors.-Economic dispatch controller added to LFC control.

UNIT V COMPUTER CONTROL OF POWER SYSTEMS 9

Energy control centre: Functions – Monitoring, data acquisition and control. System hardware configuration – SCADA and EMS functions: Network topology determination, state estimation, security analysis and control. Various operating states: Normal, alert, emergency, in-extremis and restorative-State transition diagram showing various state transitions and control strategies.

TOTAL : 45 PERIODS

REFERENCES:

1. Olle. I. Elgerd, 'Electric Energy Systems Theory – An Introduction', Tata McGraw Hill Publishing Company Ltd, New Delhi, Second Edition, 2003.
2. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Third Edition, Tata McGraw Hill Publishing Company Limited, New Delhi, 2003.
3. L.L. Grigsby, 'The Electric Power Engineering, Hand Book', CRC Press & IEEE Press, 2001
4. Allen.J.Wood and Bruce F.Wollenberg, 'Power Generation, Operation and Control', John Wiley & Sons, Inc., 2003.
5. P. Kundur, 'Power System Stability & Control', McGraw Hill Publications, USA, 1994

OBJECTIVE:

- To gain knowledge in the sources and effects of lightning, switching and temporary over voltages.
- Ability to model and estimate the over voltages in power system
- To coordinate the insulation of power system and protective devices.
- Ability to model and analyze power system and equipment for transient over voltages using Electromagnetic Transient Program (EMTP).

UNIT I LIGHTNING OVERVOLTAGES 9

Mechanism and parameters of lightning flash, protective shadow, striking distance, electrogeometric model for lightning strike, Grounding for protection against lightning – Steady-state and dynamic tower-footing resistance, substation grounding Grid, Direct lightning strokes to overhead lines, without and with shield Wires.

UNIT II SWITCHING AND TEMPORARY OVERVOLTAGES 9

Switching transients – concept – phenomenon – system performance under switching surges, Temporary over voltages – load rejection – line faults – Ferro resonance, VFTO.

UNIT III TRAVELLING WAVES ON TRANSMISSION LINE 9

Circuits and distributed constants, wave equation, reflection and refraction – behavior of travelling waves at the line terminations – Lattice Diagrams – attenuation and distortion – multi-conductor system and multi velocity waves.

UNIT IV INSULATION CO-ORDINATION 9

Classification of over voltages and insulations for insulation co-ordination– Characteristics of protective devices, applications, location of arresters – insulation co-ordination in AIS and GIS.

UNIT V COMPUTATION OF POWER SYSTEM TRANSIENTS 9

Modeling of power apparatus for transient studies – principles of digital computation – transmission lines, cables, transformer and rotating machines – Electromagnetic Transient program – case studies: line with short and open end, line terminated with R, L, C, transformer, and typical power system case study: simulation of possible over voltages in a high voltage substation.

TOTAL : 45 PERIODS

REFERENCES

1. Pritindra Chowdhari, "Electromagnetic transients in Power System", John Wiley and Sons Inc., Second Edition, 2009.
2. Allan Greenwood, "Electrical Transients in Power System", Wiley & Sons Inc. New York, 2012.
3. Klaus Ragaller, "Surges in High Voltage Networks", Plenum Press, New York, 1980.
4. Rakosh Das Begamudre, "Extra High Voltage AC Transmission Engineering", (Second edition) Newage International (P) Ltd., New Delhi, 2006.
5. Naidu M S and Kamaraju V, "High Voltage Engineering", Tata McGraw-Hill Publishing Company Ltd., New Delhi, 2004.

6. IEEE Guide for safety in AC substation grounding IEEE Standard 80-2000.
7. Working Group 33/13-09 (1988), 'Very fast transient phenomena associated with Gas Insulated System', CIGRE, 33-13, pp. 1-20.

CL7103

SYSTEM THEORY

**LTPC
3003**

OBJECTIVES

- To educate on modeling and representing systems in state variable form
- To educate on solving linear and non-linear state equations
- To illustrate the role of controllability and observability
- To educate on stability analysis of systems using Lyapunov's theory
- To educate on modal concepts and design of state and output feedback controllers and estimators

UNIT I STATE VARIABLE REPRESENTATION 9

Introduction-Concept of State-State equation for Dynamic Systems -Time invariance and linearity- Non uniqueness of state model-State Diagrams - Physical System and State Assignment.

UNIT II SOLUTION OF STATE EQUATIONS 9

Existence and uniqueness of solutions to Continuous-time state equations-Solution of Nonlinear and Linear Time Varying State equations-Evaluation of matrix exponential-System modes- Role of Eigenvalues and Eigenvectors.

UNIT III CONTROLLABILITY AND OBSERVABILITY 9

Controllability and Observability-Stabilizability and Detectability-Test for Continuous time Systems- Time varying and Time invariant case-Output Controllability-Reducibility-System Realizations.

UNIT IV STABILITY 9

Introduction-Equilibrium Points-Stability in the sense of Lyapunov-BIBO Stability-Stability of LTI Systems-Equilibrium Stability of Nonlinear Continuous Time Autonomous Systems-The Direct Method of Lyapunov and the Linear Continuous-Time Autonomous Systems-Finding Lyapunov Functions for Nonlinear Continuous Time Autonomous Systems-Krasovskii and Variable-Gradient Method.

UNIT V MODAL CONTROL 9

Introduction-Controllable and Observable Companion Forms-SISO and MIMO Systems-The Effect of State Feedback on Controllability and Observability-Pole Placement by State Feedback for both SISO and MIMO Systems-Full Order and Reduced Order Observers.

TOTAL : 45 PERIODS

REFERENCES:

1. M. Gopal, "Modern Control System Theory", New Age International, 2005.
2. K. Ogatta, "Modern Control Engineering", PHI, 2002.

3. John S. Bay, "Fundamentals of Linear State Space Systems", McGraw-Hill, 1999.
4. D. Roy Choudhury, "Modern Control Systems", New Age International, 2005.
5. John J. D'Azzo, C. H. Houpis and S. N. Sheldon, "Linear Control System Analysis and Design with MATLAB", Taylor Francis, 2003.
6. Z. Bubnicki, "Modern Control Theory", Springer, 2005.

PS7111

POWER SYSTEM SIMULATION LABORATORY

L T P C

0 0 3 1

OBJECTIVES

- To have hands on experience on various system studies and different techniques used for system planning. Software packages.
- To perform the dynamic analysis of power system

LIST OF EXPERIMENTS

1. Power flow analysis by Newton-Raphson method and Fast decoupled method
2. Transient stability analysis of single machine-infinite bus system using classical machine model
3. Contingency analysis: Generator shift factors and line outage distribution factors
4. Economic dispatch using lambda-iteration method
5. Unit commitment: Priority-list schemes and dynamic programming
6. Analysis of switching surge using EMTP: Energisation of a long distributed-parameter line
7. Analysis of switching surge using EMTP : Computation of transient recovery voltage
8. Familiarization of Relay Test Kit
9. Simulation and Implementation of Voltage Source Inverter
10. Digital Over Current Relay Setting and Relay Coordination.
11. Co-ordination of over-current and distance relays for radial line protection

TOTAL : 45 PERIODS

Lab requirements

Sl.No.	Description of Equipment	Quantity Required
1.	Personal Computers (Intel Core i3, 250 GB, 1 GB RAM)	25
2.	Laser Printer	1
3.	Dot matrix Printer	2
4.	Server (Intel Core i3, 4 GB RAM) (High Speed Processor)	1
5.	Software: EMTP / ETAP / CYME / MIPOWER / any Power system simulation software	5 Licenses
6.	Compilers: C, C++, Matlab	25 users

PS7201

POWER SYSTEM DYNAMICS

L T P C
3 0 0 3

COURSE OBJECTIVES

- To impart knowledge on dynamic modeling of a synchronous machine in detail
- To describe the modeling of excitation and speed governing system in detail.
- To understand the fundamental concepts of stability of dynamic systems and its classification
- To understand and enhance small signal stability problem of power systems.

UNIT I SYNCHRONOUS MACHINE MODELLING

9

Schematic Diagram, Physical Description: armature and field structure, machines with multiple pole pairs, mmf waveforms, direct and quadrature axes, Mathematical Description of a Synchronous Machine: Basic equations of a synchronous machine: stator circuit equations, stator self, stator mutual and stator to rotor mutual inductances, dq0 Transformation: flux linkage and voltage equations for stator and rotor in dq0 coordinates, electrical power and torque, physical interpretation of dq0 transformation, Per Unit Representations: L_{ad} -reciprocal per unit system and that from power-invariant form of Park's transformation; Equivalent Circuits for direct and quadrature axes, Steady-state Analysis: Voltage, current and flux-linkage relationships, Phasor representation, Rotor angle, Steady-state equivalent circuit, Computation of steady-state values, Equations of Motion: Swing Equation, calculation of inertia constant, Representation in system studies, Synchronous Machine Representation in Stability Studies: Simplifications for large-scale studies : Neglect of stator $p\psi$ terms and speed

variations, Simplified model with amortisseurs neglected: two-axis model with amortisseur windings neglected, classical model.

UNIT II MODELLING OF EXCITATION AND SPEED GOVERNING SYSTEMS 9

Excitation System Requirements; Elements of an Excitation System; Types of Excitation System; Control and protective functions; IEEE (1992) block diagram for simulation of excitation systems. Turbine and Governing System Modeling: Functional Block Diagram of Power Generation and Control, Schematic of a hydroelectric plant, classical transfer function of a hydraulic turbine (no derivation), special characteristic of hydraulic turbine, electrical analogue of hydraulic turbine, Governor for Hydraulic Turbine: Requirement for a transient droop, Block diagram of governor with transient droop compensation, Steam turbine modeling: Single reheat tandem compounded type only and IEEE block diagram for dynamic simulation; generic speed-governing system model for normal speed/load control function.

UNIT III SMALL-SIGNAL STABILITY ANALYSIS WITHOUT CONTROLLERS 9

Classification of Stability, Basic Concepts and Definitions: Rotor angle stability, The Stability Phenomena. Fundamental Concepts of Stability of Dynamic Systems: State-space representation, stability of dynamic system, Linearization, Eigen properties of the state matrix: Eigen values and eigenvectors, modal matrices, Eigen value and stability, mode shape and participation factor. Single-Machine Infinite Bus (SMIB) Configuration: Classical Machine Model stability analysis with numerical example, Effects of Field Circuit Dynamics: synchronous machine, network and linearised system equations, block diagram representation with K-constants; expression for K-constants (no derivation), effect of field flux variation on system stability: analysis with numerical example.

UNIT IV SMALL-SIGNAL STABILITY ANALYSIS WITH CONTROLLERS 9

Effects Of Excitation System: Equations with definitions of appropriate K-constants and simple thyristor excitation system and AVR, block diagram with the excitation system, analysis of effect of AVR on synchronizing and damping components using a numerical example, Power System Stabilizer: Block diagram with AVR and PSS, Illustration of principle of PSS application with numerical example, Block diagram of PSS with description, system state matrix including PSS, analysis of stability with numerical example. Multi-Machine Configuration: Equations in a common reference frame, equations in individual machine rotor coordinates, illustration of formation of system state matrix for a two-machine system with classical models for synchronous machines, illustration of stability analysis using a numerical example. Principle behind small-signal stability improvement methods: delta-omega and delta P-omega stabilizers.

UNIT V ENHANCEMENT OF SMALL SIGNAL STABILITY 9

Power System Stabilizer – Stabilizer based on shaft speed signal (delta omega) – Delta –P-Omega stabilizer-Frequency-based stabilizers – Digital Stabilizer – Excitation control design – Exciter gain – Phase lead compensation – Stabilizing signal washout stabilizer gain – Stabilizer limits

TOTAL : 45 PERIODS

REFERENCES:

1. P. W. Sauer and M. A. Pai, "Power System Dynamics and Stability", Stipes Publishing Co, 2007
2. IEEE Committee Report, "Dynamic Models for Steam and Hydro Turbines in Power System Studies", IEEE Trans., Vol.PAS-92, pp 1904-1915, November/December, 1973. on Turbine-Governor Model.
3. P.M Anderson and A.A Fouad, "Power System Control and Stability", Iowa State University Press, Ames, Iowa, 1978.
4. R.Ramunujam, "Power System Dynamics Analysis and Simulation, PHI Learning Private Limited, New Delhi, 2009
- 5.. P. Kundur, "Power System Stability and Control", McGraw-Hill, 1993.

PS7202

FLEXIBLE AC TRANSMISSION SYSTEMS

L T P C

3 0 0 3

OBJECTIVES

- To emphasis the need for FACTS controllers.
- To learn the characteristics, applications and modeling of series and shunt FACTS controllers.
- To analyze the interaction of different FACTS controller and perform control coordination

UNIT I INTRODUCTION

9

Review of basics of power transmission networks-control of power flow in AC transmission line- Analysis of uncompensated AC Transmission line- Passive reactive power compensation: Effect of series and shunt compensation at the mid-point of the line on power transfer- Need for FACTS controllers- types of FACTS controllers.

UNIT II STATIC VAR COMPENSATOR (SVC)

9

Configuration of SVC- voltage regulation by SVC- Modelling of SVC for load flow analysis- Modelling of SVC for stability studies-Design of SVC to regulate the mid-point voltage of a SMIB system- Applications: transient stability enhancement and power oscillation damping of SMIB system with SVC connected at the mid-point of the line.

UNIT III THYRISTOR AND GTO THYRISTOR CONTROLLED SERIES

CAPACITORS (TCSC and GCSC)

9

Concepts of Controlled Series Compensation – Operation of TCSC and GCSC- Analysis of TCSC-GCSC – Modelling of TCSC and GCSC for load flow studies-modeling TCSC and GCSC for stability studied- Applications of TCSC and GCSC.

UNIT IV VOLTAGE SOURCE CONVERTER BASED FACTS CONTROLLERS 9

Static synchronous compensator(STATCOM)- Static synchronous series compensator(SSSC)- Operation of STATCOM and SSSC-Power flow control with STATCOM and SSSC- Modelling of STATCOM and SSSC for power flow and transient stability studies –operation of Unified and Interline power flow controllers(UPFC and IPFC)- Modelling of UPFC and IPFC for load flow and transient stability studies- Applications.

UNIT V CONTROLLERS AND THEIR COORDINATION 9

FACTS Controller interactions – SVC–SVC interaction - co-ordination of multiple controllers using linear control techniques – Quantitative treatment of control coordination.

TOTAL : 45 PERIODS

REFERENCES:

1. A.T.John, “Flexible AC Transmission System”, Institution of Electrical and Electronic Engineers (IEEE), 1999.
2. Narain G.Hingorani, Laszio. Gyugyl, “Understanding FACTS Concepts and Technology of Flexible AC Transmission System”, Standard Publishers, Delhi 2001.
3. V. K.Sood, “HVDC and FACTS controllers- Applications of Static Converters in Power System”, 2004, Kluwer Academic Publishers.
4. Mohan Mathur, R., Rajiv. K. Varma, “Thyristor – Based Facts Controllers for Electrical Transmission Systems”, IEEE press and John Wiley & Sons, Inc.
5. K.R.Padiyar, ” FACTS Controllers in Power Transmission and Distribution”, New Age International(P) Ltd., Publishers New Delhi, Reprint 2008,

PS7203

ADVANCED POWER SYSTEM PROTECTION

L T P C

3 0 0 3

OBJECTIVES

- To illustrate concepts of transformer protection
- To describe about the various schemes of Over current protection
- To analyse distance and carrier protection
- To familiarize the concepts of Busbar protection and Numerical protection

UNIT I OVER CURRENT PROTECTION 9

Zones of protection – Primary and Backup protection – operating principles and Relay Construction - Time – Current characteristics-Current setting – Time setting-Over current protective schemes - Reverse power or directional relay - Protection of parallel feeders - Protection of ring feeders - Earth fault and phase fault protection -

Combined Earth fault and phase fault protection scheme - Phase fault protective scheme directional earth fault relay - Static over current relays; numerical example for a radial feeder

UNIT II EQUIPMENT PROTECTION 9

Types of transformers – Phasor diagram for a three – Phase transformer-Equivalent circuit of transformer – Types of faults in transformers- Over – current protection Percentage Differential Protection of Transformers - Inrush phenomenon-High resistance Ground Faults in Transformers - Inter-turn faults in transformers - Incipient faults in transformers - Phenomenon of over-fluxing in transformers - Transformer protection application chart .Generator protection: Electrical circuit of the generator – Various faults and abnormal operating conditions-stator faults-rotor faults –Abnormal operating conditions; numerical examples for typical transformer and generator protection schemes

UNIT III DISTANCE AND CARRIER PROTECTION OF TRANSMISSION LINES 9

Drawback of over – Current protection – Introduction to distance relay – Simple impedance relay – Reactance relay – mho relays comparison of distance relay – Distance protection of a three – Phase line-reasons for inaccuracy of distance relay reach - Three stepped distance protection - Trip contact configuration for the three - Stepped distance protection - Three-stepped protection of three-phase line against all ten shunt faults - Impedance seen from relay side - Three-stepped protection of double end fed lines-need for carrier – Aided protection – Various options for a carrier –Coupling and trapping the carrier into the desired line section - Unit type carrier aided directional comparison relaying – Carrier aided distance schemes for acceleration of zone II.; numerical example for a typical distance protection scheme for a transmission line.

UNIT IV BUSBAR PROTECTION 9

Introduction – Differential protection of busbars-external and internal fault - Actual behaviors of a protective CT - Circuit model of a saturated CT - External fault with one CT saturation :need for high impedance – Minimum internal fault that can be detected by the high – Stability ratio of high impedance busbar differential scheme - Supervisory relay-protection of three – Phase busbars-Numerical examples on design of high impedance busbar differential scheme.

UNIT V NUMERICAL PROTECTION 9

Introduction–Block diagram of numerical relay - Sampling theorem- Correlation with a reference wave–Least error squared (LES) technique-Digital filtering-numerical over - Current protection–Numerical transformer differential protection-Numerical distance protection of transmission line

TOTAL : 45 PERIODS

REFERENCES

1. P.Kundur, “Power System Stability and Control”, McGraw-Hill, 1993.
2. Protective Relaying for Power System II Stanley Horowitz ,IEEE press , New York, 2008
3. T.S.M. Rao, Digital Relay / Numerical relays , Tata McGraw Hill, New Delhi, 1989
4. Y.G. Paithankar and S.R Bhide, “Fundamentals of Power System Protection”, Prentice-Hall of India, 2003

5. Badri Ram and D.N. Vishwakarma, "Power System Protection and Switchgear", Tata McGraw- Hill Publishing Company, 2002.

PS7204

RESTRUCTURED POWER SYSTEM

LT PC

3 0 0 3

OBJECTIVES

- To Introduce the restructuring of power industry and market models.
- To impart knowledge on fundamental concepts of congestion management.
- To analyze the concepts of locational marginal pricing and financial transmission rights.
- To Illustrate about various power sectors in India

UNIT I INTRODUCTION TO RESTRUCTURING OF POWER INDUSTRY 9

Introduction: Deregulation of power industry, Restructuring process, Issues involved in deregulation, Deregulation of various power systems – Fundamentals of Economics: Consumer behavior, Supplier behavior, Market equilibrium, Short and long run costs, Various costs of production – Market models: Market models based on Contractual arrangements, Comparison of various market models, Electricity vis – a – vis other commodities, Market architecture, Case study.

UNIT II TRANSMISSION CONGESTION MANAGEMENT 9

Introduction: Definition of Congestion, reasons for transfer capability limitation, Importance of congestion management, Features of congestion management – Classification of congestion management methods – Calculation of ATC - Non – market methods – Market methods – Nodal pricing – Inter zonal and Intra zonal congestion management – Price area congestion management – Capacity alleviation method.

UNIT III LOCATIONAL MARGINAL PRICES AND FINANCIAL TRANSMISSION RIGHTS 9

Mathematical preliminaries: - Locational marginal pricing– Lossless DCOPF model for LMP calculation – Loss compensated DCOPF model for LMP calculation – ACOPF model for LMP calculation – Financial Transmission rights – Risk hedging functionality - Simultaneous feasibility test and revenue adequacy – FTR issuance process: FTR auction, FTR allocation – Treatment of revenue shortfall – Secondary trading of FTRs – Flow gate rights – FTR and market power - FTR and merchant transmission investment.

UNIT IV ANCILLARY SERVICE MANAGEMENT AND PRICING OF TRANSMISSION NETWORK 9

Introduction of ancillary services – Types of Ancillary services – Classification of Ancillary services – Load generation balancing related services – Voltage control and reactive power support devices – Black start capability service - How to obtain ancillary service –Co-optimization of energy and reserve services - International comparison

Transmission pricing – Principles – Classification – Rolled in transmission pricing methods – Marginal transmission pricing paradigm – Composite pricing paradigm – Merits and demerits of different paradigm.

UNIT V REFORMS IN INDIAN POWER SECTOR

9

Introduction – Framework of Indian power sector – Reform initiatives - Availability based tariff – Electricity act 2003 – Open access issues – Power exchange – Reforms in the near future

TOTAL : 45 PERIODS

REFERENCES

1. Sally Hunt," Making competition work in electricity", , John Willey and Sons Inc. 2002
2. Steven Stoft," Power system economics: designing markets for electricity", John Wiley & Sons, 2002.
3. Mohammad Shahidehpour, Muwaffaq Alomoush, Marcel Dekker, "Restructured electrical power systems: operation, trading and volatility" Pub., 2001
4. Kankar Bhattacharya, Jaap E. Daadler, Math H.J. Bollen," Operation of restructured power systems", Kluwer Academic Pub., 2001.

PS7211 ADVANCED POWER SYSTEM SIMULATION LABORATORY L T P C

0 0 3 1

OBJECTIVES

- To analyze the effect of FACTS controllers by performing steady state analysis.
- To have hands on experience on different wind energy conversion technologies

LIST OF EXPERIMENTS

1. Small-signal stability analysis of single machine-infinite bus system using classical machine model
2. Small-signal stability analysis of multi-machine configuration with classical machine model
3. Induction motor starting analysis
4. Load flow analysis of two-bus system with STATCOM
5. Transient analysis of two-bus system with STATCOM
6. Available Transfer Capability calculation using an existing load flow program
7. Study of variable speed wind energy conversion system- DFIG
8. Study of variable speed wind energy conversion system- PMSG

9. Computation of harmonic indices generated by a rectifier feeding a R-L load
10. Design of active filter for mitigating harmonics.

TOTAL: 45 PERIODS

Lab Requirements

Sl.No.	Description of Equipment	Quantity Required
1.	Personal Computers (Intel Core i3, 250 GB, 1 GB RAM)	25
2.	Laser Printer	1
3.	Dot matrix Printer	2
4.	Server (Intel Core i3, 4 GB RAM) (High Speed Processor)	1
5.	Software: 1. Any Power system simulation package like ETAP / MIPOWER 2. Any Power system simulation package for dynamic studies like EUROSTAG (or) own source code can be developed	5 Licenses 5 Licenses
6.	Compilers: C, C++, Matlab	25 users

PS7311

PROJECT WORK (PHASE I)

L T P C
0 0 12 6

PS7411

PROJECT WORK (PHASE II)

L T P C
0 0 24 12

OBJECTIVES

- To expose the students to the fundamentals of microcontroller based system design.
- To teach I/O and RTOS role on microcontroller.
- To impart knowledge on PIC Microcontroller based system design.
- To introduce Microchip PIC 8 bit peripheral system Design
- To give case study experiences for microcontroller based applications.

UNIT I 8051 ARCHITECTURE 9

Architecture – memory organization – addressing modes – instruction set – Timers - Interrupts - I/O ports, Interfacing I/O Devices – Serial Communication.

UNIT II 8051 PROGRAMMING 9

Assembly language programming – Arithmetic Instructions – Logical Instructions – Single bit Instructions – Timer Counter Programming – Serial Communication Programming Interrupt Programming – RTOS for 8051 – RTOSLite – FullRTOS – Task creation and run – LCD digital clock/thermometer using FullRTOS

UNIT III PIC MICROCONTROLLER 9

Architecture – memory organization – addressing modes – instruction set – PIC programming in Assembly & C – I/O port, Data Conversion, RAM & ROM Allocation, Timer programming, MP-LAB.

UNIT IV PERIPHERAL OF PIC MICROCONTROLLER 9

Timers – Interrupts, I/O ports- I2C bus-A/D converter-UART- CCP modules -ADC, DAC and Sensor Interfacing –Flash and EEPROM memories.

UNIT V SYSTEM DESIGN – CASE STUDY 9

Interfacing LCD Display – Keypad Interfacing - Generation of Gate signals for converters and Inverters - Motor Control – Controlling DC/ AC appliances – Measurement of frequency - Stand alone Data Acquisition System.

TOTAL : 45 PERIODS**REFERENCES:**

1. Muhammad Ali Mazidi, Rolin D. Mckinlay, Danny Causey ‘ PIC Microcontroller and Embedded Systems using Assembly and C for PIC18’, Pearson Education 2008
2. John Iovine, ‘PIC Microcontroller Project Book ’, McGraw Hill 2000
3. Myke Predko, “Programming and customizing the 8051 microcontroller”, Tata McGraw Hill 2001.
4. Muhammad Ali Mazidi, Janice G. Mazidi and Rolin D. McKinlay, ‘The 8051 Microcontroller and Embedded Systems’ Prentice Hall, 2005.
5. Rajkamal, “.Microcontrollers-Architecture, Programming, Interfacing & System Design”, 2ed, Pearson, 2012.
6. I Scott Mackenzie and Raphael C.W. Phan, “The Micro controller”, Pearson, Fourth edition 2012

OBJECTIVES:

- To provide knowledge about the fundamentals of magnetic circuits, energy, force and torque of multi-excited systems.
- To analyze the steady state and dynamic state operation of DC machine through mathematical modeling and simulation in digital computer.
- To provide the knowledge of theory of transformation of three phase variables to two phase variables.
- To analyze the steady state and dynamic state operation of three-phase induction machines using transformation theory based mathematical modeling and digital computer simulation.
- To analyze the steady state and dynamic state operation of three-phase synchronous machines using transformation theory based mathematical modeling and digital computer simulation.

UNIT I PRINCIPLES OF ELECTROMAGNETIC ENERGY CONVERSION 9

Magnetic circuits, permanent magnet, stored magnetic energy, co-energy - force and torque in singly and doubly excited systems – machine windings and air gap mmf - winding inductances and voltage equations.

UNIT II DC MACHINES 9

Elementary DC machine and analysis of steady state operation - Voltage and torque equations – dynamic characteristics of permanent magnet and shunt d.c. motors – Time domain block diagrams - solution of dynamic characteristic by Laplace transformation – digital computer simulation of permanent magnet and shunt D.C. machines.

UNIT III REFERENCE FRAME THEORY 9

Historical background – phase transformation and commutator transformation – transformation of variables from stationary to arbitrary reference frame - variables observed from several frames of reference.

UNIT IV INDUCTION MACHINES 9

Three phase induction machine, equivalent circuit and analysis of steady state operation – free acceleration characteristics – voltage and torque equations in machine variables and arbitrary reference frame variables – analysis of dynamic performance for load torque variations – digital computer simulation.

UNIT V SYNCHRONOUS MACHINES 9

Three phase synchronous machine and analysis of steady state operation - voltage and torque equations in machine variables and rotor reference frame variables (Park's equations) – analysis of dynamic performance for load torque variations – digital computer simulation.

TOTAL : 45 PERIODS**REFERENCES**

1. Paul C.Krause, Oleg Wasyzczuk, Scott S, Sudhoff, "Analysis of Electric Machinery and Drive Systems", John Wiley, Second Edition, 2010.

2. P S Bimbhra, "Generalized Theory of Electrical Machines", Khanna Publishers, 2008.
3. A.E, Fitzgerald, Charles Kingsley, Jr, and Stephan D, Umanx, " Electric Machinery", Tata McGraw Hill, 5th Edition, 1992

PX7103

ANALYSIS AND DESIGN OF INVERTERS

L T P C

3 0 0 3

OBJECTIVES :

- To Provide the electrical circuit concepts behind the different working modes of inverters so as to enable deep understanding of their operation.
- To equip with required skills to derive the criteria for the design of power converters for UPS, Drives etc.,
- Ability to analyse and comprehend the various operating modes of different configurations of power converters.
- Ability to design different single phase and three phase inverters.

UNIT I SINGLE PHASE INVERTERS

12

Introduction to self commutated switches : MOSFET and IGBT - Principle of operation of half and full bridge inverters – Performance parameters – Voltage control of single phase inverters using various PWM techniques – various harmonic elimination techniques – forced commutated Thyristor inverters – Design of UPS

UNIT II THREE PHASE VOLTAGE SOURCE INVERTERS

9

180 degree and 120 degree conduction mode inverters with star and delta connected loads – voltage control of three phase inverters: single, multi pulse, sinusoidal, space vector modulation techniques – Application to drive system

UNIT III CURRENT SOURCE INVERTERS

9

Operation of six-step thyristor inverter – inverter operation modes – load – commutated inverters – Auto sequential current source inverter (ASCI) – current pulsations – comparison of current source inverter and voltage source inverters – PWM techniques for current source inverters.

UNIT IV MULTILEVEL & BOOST INVERTERS

9

Multilevel concept – diode clamped – flying capacitor – cascade type multilevel inverters - Comparison of multilevel inverters - application of multilevel inverters – PWM techniques for MLI – Single phase & Three phase Impedance source inverters .

UNIT V RESONANT INVERTERS

6

Series and parallel resonant inverters - voltage control of resonant inverters – Class E resonant inverter – resonant DC – link inverters.

REFERENCES

1. Rashid M.H., "Power Electronics Circuits, Devices and Applications ", Prentice Hall India, Third Edition, New Delhi, 2004.
2. Jai P.Agrawal, "Power Electronics Systems", Pearson Education, Second Edition, 2002.
3. Bimal K.Bose "Modern Power Electronics and AC Drives", Pearson Education, Second Edition, 2003.
4. Ned Mohan, T.M Undeland and W.P Robbin, "Power Electronics: converters, Application and design" John Wiley and sons. Wiley India edition, 2006.
5. Philip T. krein, "Elements of Power Electronics" Oxford University Press -1998.
6. P.C. Sen, "Modern Power Electronics", Wheeler Publishing Co, First Edition, New Delhi, 1998.
7. P.S.Bimbra, "Power Electronics", Khanna Publishers, Eleventh Edition, 2003.

PX7204

POWER QUALITY

**L T P C
3 0 0 3**

OBJECTIVES :

- To understand the various power quality issues.
- To understand the concept of power and power factor in single phase and three phase systems supplying non linear loads
- To understand the conventional compensation techniques used for power factor correction and load voltage regulation.
- To understand the active compensation techniques used for power factor correction.
- To understand the active compensation techniques used for load voltage regulation.

UNIT I INTRODUCTION

9

Introduction – Characterisation of Electric Power Quality: Transients, short duration and long duration voltage variations, Voltage imbalance, waveform distortion, Voltage fluctuations, Power frequency variation, Power acceptability curves – power quality problems: poor load power factor, Non linear and unbalanced loads, DC offset in loads, Notching in load voltage, Disturbance in supply voltage – Power quality standards.

UNIT II ANALYSIS OF SINGLE PHASE AND THREE PHASE SYSTEM

9

Single phase linear and non linear loads – single phase sinusoidal, non sinusoidal source – supplying linear and nonlinear load – three phase Balance system – three phase unbalanced system – three phase unbalanced and distorted source supplying non linear loads – concept of pf – three phase three wire – three phase four wire system.

UNIT III CONVENTIONAL LOAD COMPENSATION METHODS

9

Principle of load compensation and voltage regulation – classical load balancing problem : open loop balancing – closed loop balancing, current balancing – harmonic

reduction and voltage sag reduction – analysis of unbalance – instantaneous of real and reactive powers – Extraction of fundamental sequence component from measured.

UNIT IV LOAD COMPENSATION USING DSTATCOM 9

Compensating single – phase loads – Ideal three phase shunt compensator structure – generating reference currents using instantaneous PQ theory – Instantaneous symmetrical components theory – Generating reference currents when the source is unbalanced – Realization and control of DSTATCOM – DSTATCOM in Voltage control mode

UNIT V SERIES COMPENSATION OF POWER DISTRIBUTION SYSTEM 9

Rectifier supported DVR – Dc Capacitor supported DVR – DVR Structure – voltage Restoration – Series Active Filter – Unified power quality conditioner.

TOTAL : 45 PERIODS

REFERENCES

1. Arindam Ghosh “Power Quality Enhancement Using Custom Power Devices”, Kluwer Academic Publishers, 2002
2. G.T.Heydt, “Electric Power Quality”, Stars in a Circle Publications, 1994(2nd edition)
3. Power Quality - R.C. Duggan
4. Power System Harmonics –A.J. Arrillaga
5. Power Electronic Converter Harmonics –Derek A. Paice.

OBJECTIVES

- To introduce the different optimization problems and techniques
- To study the fundamentals of the linear and non-linear programming problem.
- To understand the concept of dynamic programming and genetic algorithm technique

UNIT I INTRODUCTION 9

Definition, Classification of optimization problems, Classical Optimization Techniques, Single and Multiple Optimization with and without inequality constraints.

UNIT II LINEAR PROGRAMMING (LP) 9

Simplex method of solving LPP, revised simplex method, duality, Constrained optimization, Theorems and procedure, Linear programming, mathematical model, solution technique, duality.

UNIT III NON LINEAR PROGRAMMING 9

Steepest descent method, conjugates gradient method, Newton's Method, Sequential quadratic programming, Penalty function method, augmented Lagrange multiplier method.,

UNIT IV DYNAMIC PROGRAMMING (DP) 9

Multistage decision processes, concept of sub-optimization and principle of optimality, Recursive relations, Integer Linear programming, Branch and bound algorithm

UNIT V GENETIC ALGORITHM 9

Introduction to genetic Algorithm, working principle, coding of variables, fitness function, GA operators; Similarities and differences between Gas and traditional methods; Unconstrained and constrained optimization using genetic Algorithm, real coded gas, Advanced Gas, global optimization using GA, Applications to power system.

TOTAL : 45 PERIODS

REFERENCES:

1. Computational methods in Optimization, Polak , Academic Press,1971.
2. Optimization Theory with applications, Pierre D.A., Wiley Publications,1969.
3. Taha, H. A., Operations Research: An Introduction, Seventh Edition, Pearson Education Edition, Asia, New Delhi ,2002.
4. S.S. Rao,"Optimization – Theory and Applications", Wiley-Eastern Limited, 1984.
5. G.Luenberger," Introduction of Linear and Non-Linear Programming" , Wesley Publishing Company, 2011

OBJECTIVES

- To expose the concepts of feed forward neural networks.
- To provide adequate knowledge about feed back neural networks.
- To teach about the concept of fuzziness involved in various systems.
- To expose the ideas about genetic algorithm
- To provide adequate knowledge about of FLC and NN toolbox

UNIT I INTRODUCTION AND ARTIFICIAL NEURAL NETWORKS 9

Introduction of soft computing - soft computing vs. hard computing- various types of soft computing techniques- applications of soft computing-Neuron- Nerve structure and synapse- Artificial Neuron and its model- activation functions- Neural network architecture- single layer and multilayer feed forward networks- McCullochPitts neuron model- perceptron model- Adaline and Madaline- multilayer perception model- back propagation learning methods- effect of learning rule coefficient -back propagation algorithm- factors affecting back propagation training- applications.

UNIT II ARTIFICIAL NEURAL NETWORKS 9

Counter propagation network- architecture- functioning & characteristics of counter-Propagation network-Hopfield/ Recurrent network- configuration- stability constraints-associative memory- and characteristics- limitations and applications- Hopfield v/s Boltzman machine- Adaptive Resonance Theory- Architecture- classifications- Implementation and training-Associative Memory.

UNIT III FUZZY LOGIC SYSTEM 9

Introduction to crisp sets and fuzzy sets- basic fuzzy set operation and approximate reasoning. Introduction to fuzzy logic modeling and control- Fuzzification-inferencingand defuzzification-Fuzzy knowledge and rule bases-Fuzzy modeling and control schemes for nonlinear systems. Self organizing fuzzy logic control- Fuzzy logic control for nonlinear time delay system.

UNIT IV GENETIC ALGORITHM 9

Basic concept of Genetic algorithm and detail algorithmic steps-adjustment of free Parameters- Solution of typical control problems using genetic algorithm- Concept on some other search techniques like tabu search and ant colony search techniques for solving optimization problems.

UNIT V APPLICATIONS 9

GA application to power system optimization problem- Case studies: Identification and control of linear and nonlinear dynamic systems using Matlab-Neural Network toolbox. Stability analysis of Neural Network interconnection systems- Implementation of fuzzy logic controller using Matlab fuzzy logic toolbox-Stability analysis of fuzzy control systems.

TOTAL : 45 PERIODS

REFERENCES

1. Laurene V. Fausett, Fundamentals of Neural Networks: Architectures, Algorithms And Applications, Pearson Education,
2. Timothy J. Ross, "Fuzzy Logic with Engineering Applications" Wiley India.
3. Zimmermann H.J. "Fuzzy set theory and its Applications" Springer international edition, 2011.
4. David E. Goldberg, "Genetic Algorithms in Search, Optimization, and Machine Learning", Pearson Education, 2009.
5. W.T. Miller, R.S. Sutton and P.J. Webrose, "Neural Networks for Control", MIT Press, 1996.

PS7002

ENERGY MANAGEMENT AND AUDITING

L T P C

3 0 0 3

OBJECTIVES

- To study the concepts behind economic analysis and Load management.
- To emphasize the energy management on various electrical equipments and metering.
- To illustrate the concept of lighting systems and cogeneration.

UNIT I INTRODUCTION

9

Need for energy management - energy basics- designing and starting an energy management program – energy accounting -energy monitoring, targeting and reporting- energy audit process.

UNIT II ENERGY COST AND LOAD MANAGEMENT

9

Important concepts in an economic analysis - Economic models-Time value of money- Utility rate structures- cost of electricity-Loss evaluation- Load management: Demand control techniques-Utility monitoring and control system-HVAC and energy management-Economic justification

UNIT III ENERGY MANAGEMENT FOR MOTORS, SYSTEMS, AND ELECTRICAL

EQUIPMENT

9

Systems and equipment- Electric motors-Transformers and reactors-Capacitors and synchronous machines

UNIT IV METERING FOR ENERGY MANAGEMENT

9

Relationships between parameters-Units of measure-Typical cost factors- Utility meters - Timing of meter disc for kilowatt measurement - Demand meters - Paralleling of current transformers - Instrument transformer burdens-Multitasking solid-state meters - Metering location vs. requirements- Metering techniques and practical examples

UNIT V LIGHTING SYSTEMS & COGENERATION

9

Concept of lighting systems - The task and the working space -Light sources - Ballasts - Luminaries - Lighting controls-Optimizing lighting energy - Power factor and effect of harmonics on power quality - Cost analysis techniques-Lighting and energy standards

Cogeneration: Forms of cogeneration - feasibility of cogeneration- Electrical interconnection.

TOTAL : 45 PERIODS

REFERENCES

1. Reay D.A, Industrial Energy Conservation, 1stedition, Pergamon Press, 1977.
2. IEEE Recommended Practice for Energy Management in Industrial and Commercial Facilities, IEEE, 196.
3. Amit K. Tyagi, Handbook on Energy Audits and Management, TERI, 2003.
4. Barney L. Capehart, Wayne C. Turner, and William J. Kennedy, Guide to Energy Management, Fifth Edition, The Fairmont Press, Inc., 2006
5. Eastop T.D & Croft D.R, Energy Efficiency for Engineers and Technologists,. Logman Scientific & Technical, ISBN-0-582-03184, 1990.

ET7006 ADVANCED DIGITAL SIGNAL PROCESSING

L T P C
3 0 0 3

OBJECTIVES

- To expose the students to the fundamentals of digital signal processing in frequency domain& its application
- To teach the fundamentals of digital signal processing in time-frequency domain& its application
- To compare Architectures & features of Programmable DSPprocessors
- To discuss on Application development with commercial family of DSP Processors
- To design & develop logical functions of DSPprocessors with Re-Programmable logics &Devices

UNIT I INTRODUCTION TO DIGITAL SIGNAL PROCESSING

12

Introduction, A Digital Signal-Processing System, The Sampling Process, Discrete Time Sequences, Discrete Fourier Transform (DFT) and Fast Fourier Transform (FFT), Linear Time-Invariant Systems, Decimation and Interpolation, Digital Filters, FIR Filters, IIR Filters.

UNIT II WAVELET TRANSFORM

6

Introduction to continuous wavelet transform- discrete wavelet transform -orthogonal wavelet decomposition- Multiresolution Analysis-Wavelet function-DWT,bases,orthogonal Basis-Scaling function, Wavelet coefficients- ortho normal wavelets and their relationship to filter banks- Digital filtering interpolation (i) Decomposition filters, (ii) reconstruction, the signal- Example MRA- Haar & Daubechies wavelet.

UNIT III ARCHITECTURES OF COMMERCIAL DIGITAL SIGNAL PROCESSORS 12

Introduction, categorisation of DSP Processors, Fixed Point (Blackfin), Floating Point (SHARC), TI TMS 320C6xxx & OMAP processors TMS320C54X & 54xx on Basic Architecture – comparison : of functional variations of Computational building blocks, MAC, Bus Architecture and memory, Data Addressing, Parallelism and pipelining, Parallel I/O interface, Memory Interface, Interrupt, DMA (one example Architecture in each of these case studies).

UNIT IV INTERFACING I/O PERIPHERALS FOR DSP BASED APPLICATIONS 6

Introduction, External Bus Interfacing Signals, Memory Interface, Parallel I/O Interface, Programmed I/O, Interrupts and I / O Direct Memory Access (DMA).-Introduction, Design of Decimation and Interpolation Filter, FFT Algorithm, PID Controller ,Application for Serial Interfacing, DSP based Power Meter, Position control , CODEC Interface .

UNIT V VLSI IMPLEMENTATION 9

Low power Design-need for Low power VLSI chips-Basics of DSP system architecture design using VHDL programming, Mapping of DSP algorithm onto hardware, Realisation of MAC & Filter structure.

TOTAL : 45 PERIODS

REFERENCES:

1. John G. Proakis, Dimitris G. Manolakis, "Digital Signal Processing", Pearson Education 2002.
2. Avatar Sing, S. Srinivasan, "Digital Signal Processing- Implementation using DSP Microprocessors with Examples from TMS320C54xx", Thomson India, 2004.
3. Lars Wanhammer, "DSP Integrated Circuits", Academic press, 1999, New York.
4. Lyla B Das, "Embedded Systems-An Integrated Approach", Pearson 2013
5. Ashok Ambardar, "Digital Signal Processing: A Modern Introduction", Thomson India edition, 2007.
6. Raghuvver M. Rao and Ajit S. Bapardikar, Wavelet transforms- Introduction to theory and applications, Pearson Education, 2000.
7. K.P. Soman and K.L. Ramchandran, Insight into WAVELETS from theory to practice, Eastern Economy Edition, 2008
8. Ifeachor E. C., Jervis B. W, "Digital Signal Processing: A practical approach, Pearson-Education, PHI/ 2002
9. B Venkataramani and M Bhaskar "Digital Signal Processors", TMH, 2nd, 2010
10. Peter Pirsch "Architectures for Digital Signal Processing", John Wiley, 2007
11. Vinay K. Ingle, John G. Proakis, "DSP-A Matlab Based Approach", Cengage Learning, 2010
12. Taan S. Elali, "Discrete Systems and Digital Signal Processing with Matlab", CRC Press 2009.

- To illustrate the concept of distributed generation
- To analyze the impact of grid integration.
- To study concept of Microgrid and its configuration

UNIT I INTRODUCTION 9

Conventional power generation: advantages and disadvantages, Energy crises, Non-conventional energy (NCE) resources: review of Solar PV, Wind Energy systems, Fuel Cells, micro-turbines, biomass, and tidal sources.

UNIT II DISTRIBUTED GENERATIONS (DG) 9

Concept of distributed generations, topologies, selection of sources, regulatory standards/ framework, Standards for interconnecting Distributed resources to electric power systems: IEEE 1547. DG installation classes, security issues in DG implementations. Energy storage elements: Batteries, ultra-capacitors, flywheels. Captive power plants

UNIT III IMPACT OF GRID INTEGRATION 9

Requirements for grid interconnection, limits on operational parameters, voltage, frequency, THD, response to grid abnormal operating conditions, islanding issues. Impact of grid integration with NCE sources on existing power system: reliability, stability and power quality issues.

UNIT IV BASICS OF A MICROGRID 9

Concept and definition of microgrid, microgrid drivers and benefits, review of sources of microgrids, typical structure and configuration of a microgrid, AC and DC microgrids, Power Electronics interfaces in DC and AC microgrids,

UNIT V CONTROL AND OPERATION OF MICROGRID 9

Modes of operation and control of microgrid: grid connected and islanded mode, Active and reactive power control, protection issues, anti-islanding schemes: passive, active and communication based techniques, microgrid communication infrastructure, Power quality issues in microgrids, regulatory standards, Microgrid economics, Introduction to smart microgrids.

TOTAL : 45 PERIODS

REFERENCES

1. "Voltage Source Converters in Power Systems: Modeling, Control and Applications", Amirnaser Yazdani, and Reza Iravani, IEEE John Wiley Publications.
2. "Power Switching Converters: Medium and High Power", Dorin Neacsu, CRC Press, Taylor & Francis, 2006.
3. "Solar Photo Voltaics", Chetan Singh Solanki, PHI learning Pvt. Ltd., New Delhi, 2009
4. "Wind Energy Explained, theory design and applications," J.F. Manwell, J.G. McGowan Wiley publication
5. "Biomass Regenerable Energy", D. D. Hall and R. P. Grover, John Wiley, New York, 1987.

6. "Renewable Energy Resources" John Twidell and Tony Weir, Tylor and Francis Publications, Second edition

**PS7004 SOLAR AND ENERGY STORAGE SYSTEMS L T P C
3 0 0 3**

OBJECTIVES

- To Study about solar modules and PV system design and their applications
- To Deal with grid connected PV systems
- To Discuss about different energy storage systems

UNIT I INTRODUCTION 9

Characteristics of sunlight – semiconductors and P-N junctions –behavior of solar cells – cell properties – PV cell interconnection

UNIT II STAND ALONE PV SYSTEM 9

Solar modules – storage systems – power conditioning and regulation - protection – stand alone PV systems design – sizing

UNIT III GRID CONNECTED PV SYSTEMS 9

PV systems in buildings – design issues for central power stations – safety – Economic aspect – Efficiency and performance - International PV programs

UNIT IV ENERGY STORAGE SYSTEMS 9

Impact of intermittent generation – Battery energy storage – solar thermal energy storage – pumped hydroelectric energy storage

UNIT V APPLICATIONS 9

Water pumping – battery chargers – solar car – direct-drive applications –Space – Telecommunications.

REFERENCES:

1. Eduardo Lorenzo G. Araujo, Solar electricity engineering of photovoltaic systems, Progensa,1994.
2. Stuart R.Wenham, Martin A.Green, Muriel E. Watt and Richard Corkish, Applied Photovoltaics, 2007,Earthscan, UK.
3. Frank S. Barnes & Jonah G. Levine, Large Energy storage Systems Handbook , CRC Press, 2011.
4. Solar & Wind Energy Technologies – McNeils, Frenkel, Desai, Wiley Eastern, 1990
5. Solar Energy – S.P. Sukhatme, Tata McGraw Hill,1987.

OBJECTIVES

- To impart knowledge on operation, modelling and control of HVDC link.
- To perform steady state analysis of AC/DC system.
- To expose various HVDC simulators.

UNIT I DC POWER TRANSMISSION TECHNOLOGY 6

Introduction - Comparison of AC and DC transmission – Application of DC transmission – Description of DC transmission system - Planning for HVDC transmission – Modern trends in DC transmission – DC breakers – Cables, VSC based HVDC.

UNIT II ANALYSIS OF HVDC CONVERTERS AND HVDC SYSTEM CONTROL 12

Pulse number, choice of converter configuration – Simplified analysis of Graetz circuit - Converter bridge characteristics – characteristics of a twelve pulse converter- detailed analysis of converters- General principles of DC link control – Converter control characteristics – System control hierarchy - Firing angle control – Current and extinction angle control – Generation of harmonics and filtering - power control – Higher level controllers.

UNIT III MULTITERMINAL DC SYSTEMS 9

Introduction – Potential applications of MTDC systems - Types of MTDC systems - Control and protection of MTDC systems - Study of MTDC systems.

UNIT IV POWER FLOW ANALYSIS IN AC/DC SYSTEMS 9

Per unit system for DC Quantities - Modelling of DC links - Solution of DC load flow - Solution of AC-DC power flow – Unified, Sequential and Substitution of power injection method.

UNIT V SIMULATION OF HVDC SYSTEMS 9

Introduction – DC LINK Modelling , Converter Modeling and State Space Analysis , Philosophy and tools – HVDC system simulation, Online and OFFline simulators — Dynamic interactions between DC and AC systems.

TOTAL: 45 PERIODS

REFERENCES

1. P. Kundur, "Power System Stability and Control", McGraw-Hill, 1993
2. K.R.Padiyar, , "HVDC Power Transmission Systems", New Age International (P) Ltd., New Delhi, 2002.
3. J.Arrillaga, , "High Voltage Direct Current Transmission", Peter Pregrinus, London, 1983.
4. Erich Uhlmann, " Power Transmission by Direct Current", BS Publications, 2004.
5. V.K.Sood,HVDC and FACTS controllers – Applications of Static Converters in Power System, APRIL 2004 , Kluwer Academic Publishers.

OBJECTIVES

- To analyze the motor starting and power factor correction.
- To perform computer-aided harmonic and flicker analysis and to design filters.
- To expose various grid grounding methodologies

UNIT I MOTOR STARTING STUDIES 9

Introduction-Evaluation Criteria-Starting Methods-System Data-Voltage Drop Calculations-Calculation of Acceleration time-Motor Starting with Limited-Capacity Generators-Computer-Aided Analysis-Conclusions.

UNIT II POWER FACTOR CORRECTION STUDIES 9

Introduction-System Description and Modeling-Acceptance Criteria-Frequency Scan Analysis-Voltage Magnification Analysis-Sustained Overvoltages-Switching Surge Analysis-Back-to-Back Switching-Summary and Conclusions.

UNIT III HARMONIC ANALYSIS 9

Harmonic Sources-System Response to Harmonics-System Model for Computer-Aided Analysis-Acceptance Criteria-Harmonic Filters-Harmonic Evaluation-Case Study-Summary and Conclusions.

UNIT IV FLICKER ANALYSIS 9

Sources of Flicker-Flicker Analysis-Flicker Criteria-Data for Flicker analysis- Case Study-Arc Furnace Load-Minimizing the Flicker Effects-Summary.

UNIT V GROUND GRID ANALYSIS 9

Introduction-Acceptance Criteria-Ground Grid Calculations-Computer-Aided Analysis - Improving the Performance of the Grounding Grids-Conclusions.

TOTAL : 45 PERIODS**REFERENCES**

1. Ramasamy Natarajan, "Computer-Aided Power System Analysis", Marcel Dekker Inc., 2002.

OBJECTIVES

- To learn the design and control principles of Wind turbine
- To understand the concepts of fixed speed and variable speed, wind energy conversion systems
- To analyze the grid integration issues.

UNIT I INTRODUCTION 9

Components of WECS-WECS schemes-Power obtained from wind-simple momentum theory-Power coefficient- Sabinin's theory-Aerodynamics of Wind turbine

UNIT II WIND TURBINES 9

HAWT-VAWT-Power developed-Thrust-Efficiency-Rotor selection-Rotor design considerations-Tip speed ratio-No. of Blades-Blade profile-Power Regulation-yaw control-Pitch angle control-stall control-Schemes for maximum power extraction.

UNIT III FIXED SPEED SYSTEMS 9

Generating Systems- Constant speed constant frequency systems -Choice of Generators-Deciding factors-Synchronous Generator-Squirrel Cage Induction Generator- Model of Wind Speed- Model wind turbine rotor - Drive Train model-Generator model for Steady state and Transient stability analysis.

UNIT IV VARIABLE SPEED SYSTEMS 9

Need of variable speed systems-Power-wind speed characteristics-Variable speed constant frequency systems synchronous generator- DFIG- PMSG -Variable speed generators modeling - Variable speed variable frequency schemes.

UNIT V GRID CONNECTED SYSTEMS 9

Wind interconnection requirements, low-voltage ride through (LVRT), ramp rate limitations, and supply of ancillary services for frequency and voltage control, current practices and industry trends wind interconnection impact on steady-state and dynamic performance of the power system including modeling issue.

TOTAL: 45 PERIODS**REFERENCES**

1. L.L.Freris "Wind Energy conversion Systems", Prentice Hall, 1990
2. S.N.Bhadra, D.Kastha,S.Banerjee,"Wind Electrical Sytems",Oxford University Press,2010.
3. Ion Boldea, "Variable speed generators", Taylor & Francis group, 2006.
4. E.W.Golding "The generation of Electricity by wind power", Redwood burn Ltd., Trowbridge,1976.
5. N. Jenkins," Wind Energy Technology" John Wiley & Sons,1997
6. S.Heir "Grid Integration of WECS", Wiley 1998.

OBJECTIVES

- To Study about Smart Grid technologies, different smart meters and advanced metering infrastructure.
- To familiarize the power quality management issues in Smart Grid.
- To familiarize the high performance computing for Smart Grid applications

UNIT I INTRODUCTION TO SMART GRID 9

Evolution of Electric Grid, Concept, Definitions and Need for Smart Grid, Smart grid drivers, functions, opportunities, challenges and benefits, Difference between conventional & Smart Grid, Concept of Resilient & Self Healing Grid, Present development & International policies in Smart Grid, Diverse perspectives from experts and global Smart Grid initiatives.

UNIT II SMART GRID TECHNOLOGIES 9

Technology Drivers, Smart energy resources, Smart substations, Substation Automation, Feeder Automation ,Transmission systems: EMS, FACTS and HVDC, Wide area monitoring, Protection and control, Distribution systems: DMS, Volt/VAr control, Fault Detection, Isolation and service restoration, Outage management, High-Efficiency Distribution Transformers, Phase Shifting Transformers, Plug in Hybrid Electric Vehicles (PHEV).

UNIT III SMART METERS AND ADVANCED METERING INFRASTRUCTURE 9

Introduction to Smart Meters, Advanced Metering infrastructure (AMI) drivers and benefits, AMI protocols, standards and initiatives, AMI needs in the smart grid, Phasor Measurement Unit(PMU), Intelligent Electronic Devices(IED) & their application for monitoring & protection.

UNIT IV POWER QUALITY MANAGEMENT IN SMART GRID 9

Power Quality & EMC in Smart Grid, Power Quality issues of Grid connected Renewable Energy Sources, Power Quality Conditioners for Smart Grid, Web based Power Quality monitoring, Power Quality Audit.

UNIT V HIGH PERFORMANCE COMPUTING FOR SMART GRID APPLICATIONS 9

Local Area Network (LAN), House Area Network (HAN), Wide Area Network (WAN), Broadband over Power line (BPL), IP based Protocols, Basics of Web Service and CLOUD Computing to make Smart Grids smarter, Cyber Security for Smart Grid.

TOTAL : 45 PERIODS**REFERENCES:**

1. Vehbi C. Güngör, Dilan Sahin, Taskin Kocak, Salih Ergüt, Concettina Buccella, Carlo Cecati, and Gerhard P. Hancke, Smart Grid Technologies: Communication Technologies and Standards IEEE Transactions On Industrial Informatics, Vol. 7, No. 4, November 2011.

2. Xi Fang, Satyajayant Misra, Guoliang Xue, and Dejun Yang “Smart Grid – The New and Improved Power Grid: A Survey” , IEEE Transaction on Smart Grids,
3. Stuart Borlase “Smart Grid :Infrastructure, Technology and Solutions”,CRC Press 2012.
4. Janaka Ekanayake, Nick Jenkins, KithsiriLiyanage, Jianzhong Wu, Akihiko Yokoyama, “Smart Grid: Technology and Applications”, Wiley.

PS7009

ADVANCED POWER SYSTEM DYNAMICS

LT P C

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OBJECTIVES

- To perform transient stability analysis using unified algorithm.
- To impart knowledge on sub-synchronous resonance and oscillations
- To analyze voltage stability problem in power system.
- To familiarize the methods of transient stability enhancement.

UNIT I TRANSIENT STABILITY ANALYSIS

9

Review of numerical integration methods: Euler and Fourth Order Runge-Kutta methods, Numerical stability and implicit methods, Interfacing of Synchronous machine (variable voltage) model to the transient stability algorithm (TSA) with partitioned – explicit and implicit approaches – Interfacing SVC with TSA-methods to enhance transient stability.

UNIT II UNIFIED ALGORITHM FOR DYNAMIC ANALYSIS OF POWER SYSTEMS

9

Need for unified algorithm- numerical integration algorithmic steps-truncation error-variable step size – handling the discontinuities- numerical stability- application of the algorithm for transient. Mid-term and long-term stability simulations

UNIT III SUBSYNCHRONOUS RESONANCE (SSR) AND OSCILLATIONS

9

Subsynchronous Resonance (SSR) – Types of SSR - Characteristics of series – Compensated transmission systems –Modeling of turbine-generator-transmission network- Self-excitation due to induction generator effect – Torsional interaction resulting in SSR –Methods of analyzing SSR – Numerical examples illustrating instability of subsynchronous oscillations –time-domain simulation of subsynchronous resonance – EMTP with detailed synchronous machine model- Turbine Generator Torsional Characteristics: Shaft system model – Examples of torsional characteristics – Torsional Interaction with Power System Controls: Interaction with generator excitation controls – Interaction with speed governors – Interaction with nearby DC converters.

UNIT IV TRANSMISSION, GENERATION AND LOAD ASPECTS OF VOLTAGE

STABILITY ANALYSIS

9

Review of transmission aspects – Generation Aspects: Review of synchronous machine theory – Voltage and frequency controllers – Limiting devices affecting voltage stability – Voltage-reactive power characteristics of synchronous generators – Capability curves – Effect of machine limitation on deliverable power – Load Aspects – Voltage dependence of loads – Load restoration dynamics – Induction motors – Load tap changers – Thermostatic load recovery – General aggregate load models.

UNIT V ENHANCEMENT OF TRANSIENT STABILITY AND COUNTER MEASURES

FOR SUB SYNCHRONOUS RESONANCE [1]

9

Principle behind transient stability enhancement methods: high-speed fault clearing, reduction of transmission system reactance, regulated shunt compensation, dynamic braking, reactor switching, independent pole-operation of circuit-breakers, single-pole switching, fast-valving, high-speed excitation systems; NGH damper scheme.

TOTAL : 45 PERIODS

REFERENCES:

1. R.Ramnujam," Power System Dynamics Analysis and Simulation, PHI Learning Private Limited, New Delhi, 2009
2. T.V. Cutsem and C.Vournas, "Voltage Stability of Electric Power Systems", Kluwer publishers,1998.
3. P. Kundur, Power System Stability and Control, McGraw-Hill, 1993.
4. H.W. Dommel and N.Sato, "Fast Transient Stability Solutions," IEEE Trans., Vol. PAS-91, pp, 1643-1650, July/August 1972.
5. Roderick J . Frowd and J. C. Giri, "Transient stability and Long term dynamics unified", IEEE Trans., Vol 101, No. 10, October 1982.
6. M.Stubbe, A.Bihain,J.Deuse, J.C.Baader, "A New Unified software program for the study of the dynamic behaviour of electrical power system," IEEE Transaction, Power Systems, Vol.4.No.1,Feb:1989 Pg.129 to 138.

OBJECTIVES :

- To Provide knowledge about the stand alone and grid connected renewable energy systems.
- To equip with required skills to derive the criteria for the design of power converters for renewable energy applications.
- To analyse and comprehend the various operating modes of wind electrical generators and solar energy systems.
- To design different power converters namely AC to DC, DC to DC and AC to AC converters for renewable energy systems.
- To develop maximum power point tracking algorithms.

UNIT I INTRODUCTION 9

Environmental aspects of electric energy conversion: impacts of renewable energy generation on environment (cost-GHG Emission) - Qualitative study of different renewable energy resources ocean, Biomass, Hydrogen energy systems : operating principles and characteristics of: Solar PV, Fuel cells, wind electrical systems-control strategy, operating area.

UNIT II ELECTRICAL MACHINES FOR RENEWABLE ENERGY CONVERSION 9

Review of reference theory fundamentals-principle of operation and analysis: IG, PMSG, SCIG and DFIG.

UNIT III POWER CONVERTERS 9

Solar: Block diagram of solar photo voltaic system : line commutated converters (inversion-mode) - Boost and buck-boost converters- selection Of inverter, battery sizing, array sizing.

Wind: three phase AC voltage controllers- AC-DC-AC converters: uncontrolled rectifiers, PWM Inverters, Grid Interactive Inverters-matrix converters.

UNIT IV ANALYSIS OF WIND AND PV SYSTEMS 9

Stand alone operation of fixed and variable speed wind energy conversion systems and solar system-Grid connection Issues -Grid integrated PMSG and SCIG Based WECS- Grid Integrated solar system

UNIT V HYBRID RENEWABLE ENERGY SYSTEMS 9

Need for Hybrid Systems- Range and type of Hybrid systems- Case studies of Wind-PV- Maximum Power Point Tracking (MPPT).

TOTAL : 45 PERIODS

REFERENCES:

1. S.N.Bhadra, D. Kastha, & S. Banerjee "Wind Electrical Systems", Oxford University Press, 2009
2. Rashid .M. H "power electronics Hand book", Academic press, 2001.
3. Rai. G.D, "Non conventional energy sources", Khanna publishes, 1993.
4. Rai. G.D," Solar energy utilization", Khanna publishes, 1993.
5. Gray, L. Johnson, "Wind energy system", prentice hall linc, 1995.
6. Non-conventional Energy sources B.H.Khan Tata McGraw-hill Publishing Company, New Delhi.

Pre-requisites: Basic Instrumentation ,Material Science,Programming

OBJECTIVES

- To teach the students properties of materials ,microstructure and fabrication methods.
- To teach the design and modeling of Electrostatic sensors and actuators.
- To teach the characterizing thermal sensors and actuators through design and modeling
- To teach the fundamentals of piezoelectric sensors and actuators
- To give exposure to different MEMS and NEMS devices.

UNIT I MEMS:MICRO-FABRICATION, MATERIALS AND ELECTRO-MECHANICAL CONEPTS 9

Overview of micro fabrication – Silicon and other material based fabrication processes – Concepts: Conductivity of semiconductors-Crystal planes and orientation-stress and strain-flexural beam bending analysis-torsional deflections-Intrinsic stress- resonant frequency and quality factor.

UNIT II ELECTROSTATIC SENSORS AND ACTUATION 9

Principle, material, design and fabrication of parallel plate capacitors as electrostatic sensors and actuators-Applications

UNIT III THERMAL SENSING AND ACTUATION 9

Principle, material, design and fabrication of thermal couples, thermal bimorph sensors, thermal resistor sensors-Applications.

UNIT IV PIEZOELECTRIC SENSING AND ACTUATION 9

Piezoelectric effect-cantilever piezo electric actuator model-properties of piezoelectric materials-Applications.

UNIT V CASE STUDIES 9

Piezoresistive sensors, Magnetic actuation, Micro fluidics applications, Medical applications, Optical MEMS.-NEMS Devices

TOTAL : 45 PERIODS

REFERENCES

1. Chang Liu, “Foundations of MEMS”, Pearson International Edition, 2006.
2. Marc Madou , “Fundamentals of microfabrication”,CRC Press, 1997.
3. Boston , “Micromachined Transducers Sourcebook”,WCB McGraw Hill, 1998.
4. M.H.Bao “Micromechanical transducers :Pressure sensors, accelerometers and gyroscopes”, Elsevier, Newyork, 2000.
5. P. RaiChoudry“ MEMS and MOEMS Technology and Applications”, PHI, 2012.
6. Stephen D. Senturia, “ Microsystem Design”, Springer International Edition, 2011.

OBJECTIVES

- To introduces the objectives of Load forecasting.
- To study the fundamentals of Generation system, transmission system and Distribution system reliability analysis
- To illustrate the basic concepts of Expansion planning

UNIT I LOAD FORECASTING 9

Objectives of forecasting - Load growth patterns and their importance in planning - Load forecasting Based on discounted multiple regression technique-Weather sensitive load forecasting-Determination of annual forecasting-Use of AI in load forecasting.

UNIT II GENERATION SYSTEM RELIABILITY ANALYSI 9

Probabilistic generation and load models- Determination of LOLP and expected value of demand not served –Determination of reliability of iso and interconnected generation systems.

UNIT III TRANSMISSION SYSTEM RELIABILITY ANALYSIS 9

Deterministic contingency analysis-probabilistic load flow-Fuzzy load flow probabilistic transmission system reliability analysis-Determination of reliability indices like LOLP and expected value of demand not served.

UNIT IV EXPANSION PLANNING 9

Basic concepts on expansion planning-procedure followed for integrate transmission system planning, current practice in India-Capacitor placer problem in transmission system and radial distributions system.

UNIT V DISTRIBUTION SYSTEM PLANNING OVERVIEW 9

Introduction, sub transmission lines and distribution substations-Design primary and secondary systems-distribution system protection and coordination of protective devices.

TOTAL: 45 PERIODS**REFERENCES:**

1. Reliability Evaluation of Power System - Roy Billinton & Ronald N. Allan, Springer Publication
2. Power System Planning - R.L. Sullivan, Tata McGraw Hill Publishing Company Ltd.
3. Modern Power System Planning – X. Wang & J.R. McDonald, McGraw Hill Book Company
4. Electrical Power Distribution Engineering - T. Gönen, McGraw Hill Book Company
5. Generation of Electrical Energy – B.R. Gupta, S. Chand Publications